



Goal Structuring Notation in a Radiation Hardening Assurance Case for COTS-Based Spacecraft

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List of Acronyms



Addr = Address

AMSAT = Radio Amateur Satellite Corporation

CDH = Command and Data Handling (bus and processor)

COTS = commercial off the shelf

FPF2006/2007/2123 = Fairchild Semiconductor family of load switches

GSN = Goal Structured Notation

I/O = input/output

IUCF = Indiana University Cyclotron Facility

LEO = Low-Earth Orbit

MA = mission assurance

R & M = reliability and maintainability

REM = Radiation Effects Modeling (SRAM circuit board & experiment)

RXTX = Receiver and Transmitter

SEE = Single Event Effect

SELs = Single Event Latchups

SEUs = Single Event Upsets

SRAM = Synchronous Random Access Memory

TID = Total Ionizing Dose

VU Cube Sat = Vanderbilt University CubeSat

WDT = Watchdog Timer

WebGME = Web-based Generic Modeling Environment (software)

Background: Mission Assurance

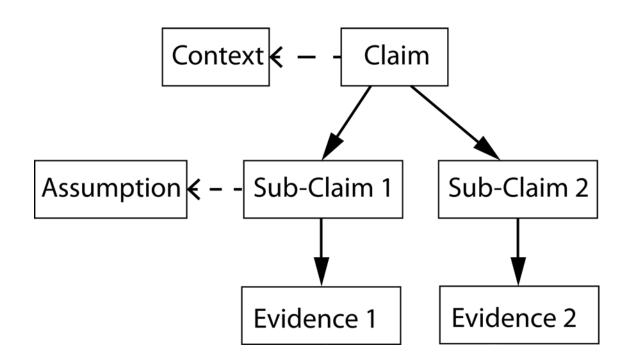


- NASA classifies spacecraft missions by criteria: Cost, national significance, priority, lifetime, launch constraints
 - Class A: High-budget, highly significant, e.g. space telescope
 - Low risk tolerance: Conventional radiation testing, hardened parts, etc.
 - (Sub) Class D: Low-budget, limited scope, short lifetime: CubeSat
 - Relatively high risk tolerance
 - Conventional radiation hardness assurance too expensive
 - Majority use of commercial off-the-shelf (COTS) parts
 - Still need as much mission assurance as possible
- Model-Based representations of spacecraft systems can define sub-system functionality and interfacing, reliability parameters
 - Quantitative evaluation of sub-system interactions
 - Entire team works from one virtual model set
 - Fault or failures can be propagated from one sub-system to another
- New paradigm for assurance: model-centric, not document-centric



Graphical Argument





Argument: "A connected series of claims intended to support an overall claim." [1]

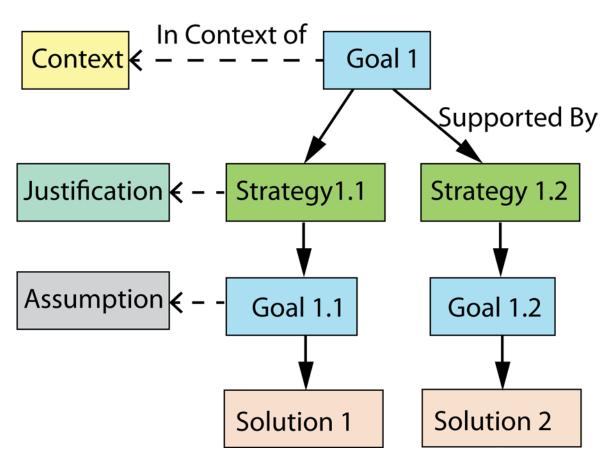
Assurance Case: "A reasoned and compelling argument, supported by a body of evidence, that a system, service or organization will operate as intended for a defined application in a defined environment." [1]

[1] GSN Community Standard Version 1 2011



Goal Structuring Notation (GSN)





GSN is a visual representation of a hierarchy of claims [1]

University of York U.K.

Goal=Claim
Strategy=Inference
Solution=Evidence
Context=Background
Justification=Rationale
Assumption=Unsubstantiated Claim

Colors/Shapes Denote Function

[1] GSN Community Standard Version 1 2011



Benefits of GSN



- Clarifies relationships between claims and makes assumptions explicit
- Facilitates connecting mission assurance claims to model-based representations of the system
 - Document-centric/model-centric mission assurance (MA)
 - Eventual goal: connect MA and quantitative models
- Construct graphical assurance case concurrently with design allows designers to address MA early
- Radiation Context:
 - References radiation test data, hardened part specs
 - Relates mitigation strategy to overall Assurance Case



Vanderbilt Custom GSN Modeling Language

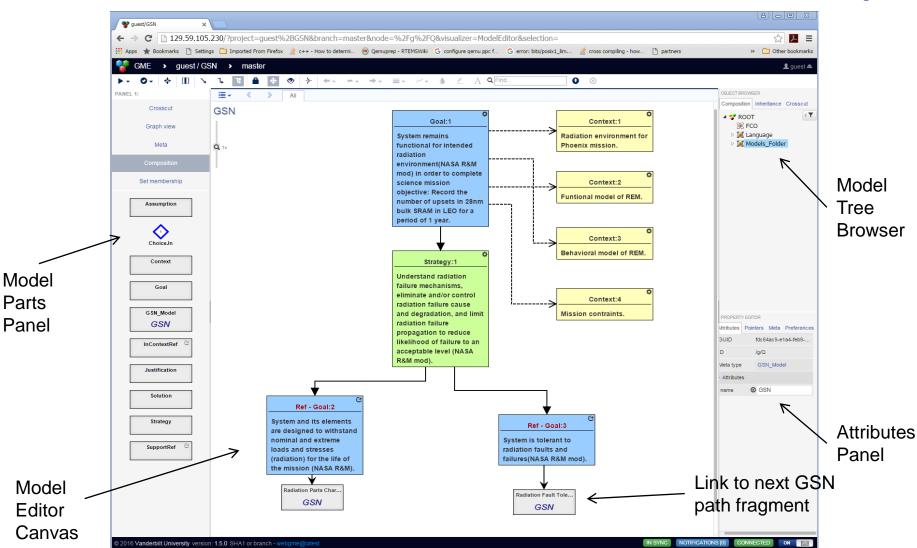


- WebGME: Web-based Generic Modeling Environment
 - Developed by Vanderbilt Institute for Software Integrated Systems
 - Used to develop modeling framework for Goal Structured Notation Support for customizable Domain Specific Modeling Languages (DSML)
 - Customizable modeling rules (meta-models) specify the syntax and semantics of the model
 - Model elements may contain hyperlinks to to engineering documents and relevant artifacts
- Support for model interpretation
 - Model interpreter algorithms traverse models to generate artifacts documents, code, inputs for integrating with other software/ utilities/ analysis engines
 - Provides framework for linking to model-based descriptions of subsystems



WebGME GSN Screenshot





NASA Reliability & Maintainability Template



Objective: System remains functional for intended lifetime, environment, operating conditions and usage Context: Description of operating environment. including static, cyclical, and randomly varying loads Strategy: Understand failure mechanisms, eliminate and/or control failure causes, degradation and common cause failures, and limit failure propagation to reduce likelihood of failure to an acceptable level Strategy: Assess quantitative reliability measures and recommend or support changes to system design and/or operations

Objectives-based approach to Reliability and Maintainability

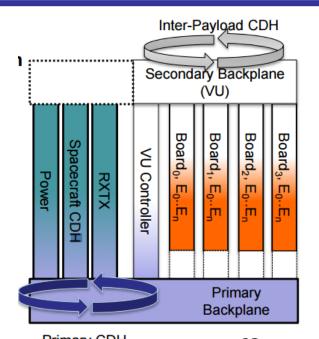
General structure for top-level goals for GSN assurance case

[2] Groen, F.J.; Evans, J.W.; Hall, A.J., "A Vision for Spaceflight Reliability: NASA's Objectives Based Strategy," RAMS, 2015, 26-29 Jan. 2015

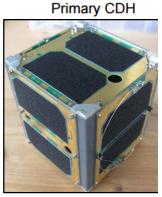


VU CubeSat SRAM Experiment Test Bed





- VU CubeSat payload architecture
- Space environment radiation testbed for TID, SEE
- Successful 8 x 4Mb SRAM experiment, launched 2015, reports SEUs, resets, power



Daily Upsets

12 10 8 6 4 2 0 Day

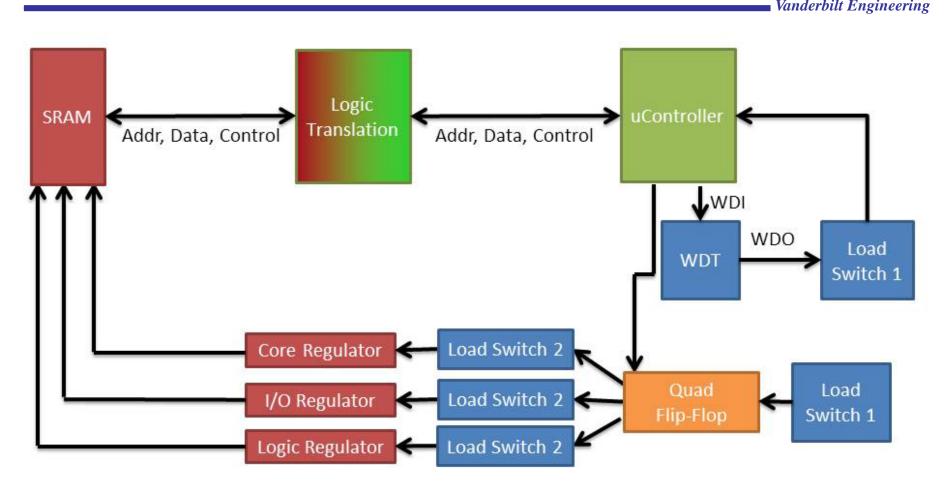
Image Credit: AMSAT

GSN Demo Case: 28nm Commercial SRAM SEU Test in LEO

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- Launch January 2017
- Radiation Effects Modeling (REM) Board
- SEU detection in the SRAM
 - Protect data from other SEEs on the board
 - Count upsets from SEUs in SRAM, not SELs
- Current monitors for latch up detection
 - Monitor separate for SRAM and other components
 - High-current on SRAM causes the experiment to reset and not count recent upsets
 - High-current on the rest of the board causes the microcontroller to reset while the SRAM continues to hold data

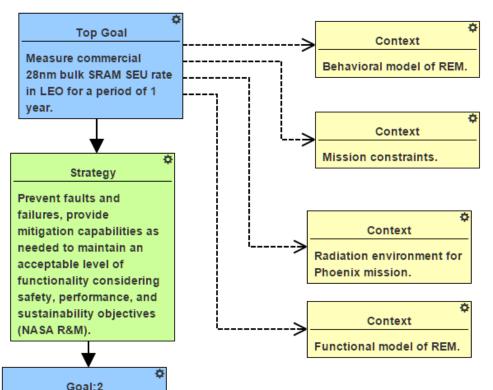
Block Diagram SRAM SEU Experiment Board



Sub-Class D: Allow latch-up, employ mitigation Current monitors, watch-dog timer sense SEL

GSN Assurance REM SEU Experiment Board





- Top Goal states overall objective
- Context statements give easy access to relevant mission docs
- Top-level goals and strategies track NASA R&M template

System remains functional for intended lifetime, environment, operating conditions and usage (NASA R&M).

GSN Assurance REM SEU Experiment Board

↓From Goal 2 Strategy: 2.A Not all branches of GSN Understand failure mechanisms, eliminate and/or control failure graph shown causes, degradation and common cause failures, Assumptions are clearly and limit failure propagation to reduce likelihood of failure to an identified acceptable level (NASA R&M). Argument path Goal:2.A.1 terminates in Solution System and its elements are designed to withstand Validity of assurance nominal and extreme loads and stresses (radiation) for the life of case determined by the mission (NASA R&M). Justification reading from Solutions to Only performed proton tests for SEL. Heavy ion Strategy: 2.A.1.D tests were not performed top-level goals. Perform qualification because the heavy ion testing to verify design environment does not for intended use (NASA significantly contribute to the mission environment. Mission constraints on budget also limited the Assumption amount of testing. Goal: 2.A.1.D.1 Goal:2.A.1.A.2 FPF2006 and FPF2007 are Load Switch 1(FPF2006) Load Switch 2(FPF2123) similar enough that the passes SEL mission passes SEL mission SEL results from FPF2007 requirement. requirement. can be used for FPF 2006. Solution Solution Results from IUCF: No Results from IUCF: No latch-up seen on FPF2007 latch-up seen on FPF2123

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Summary: Graphical Assurance Case Argument in Goal Structuring Notation



- Dependence of argument claims made explicit
- Structure imposes rigor on assurance case
- Surfaces assumptions implicit in text arguments
- Graphical form naturally compatible with modelbased descriptions of systems: SysML, CyPhyML
- Custom GSN modeling language in development
- GSN example demonstrated in design of CubeSat SRAM SEU experiment circuit board
- Graphical assurance case helps designers address mission assurance concerns during design

